

Functional Data Structures

Exercise Sheet 12

Exercise 12.1 Balanced Queues

Consider locale *Queue* in file *Thys/Amortized_Examples*. A call of *deq* (*xs*,[]) requires the reversal of *xs*, which may be very long. We can reduce that impact by shifting *xs* over to *ys* whenever *length xs > length ys*. This does not improve the amortized complexity (in fact it increases it by 1) but reduces the worst case complexity of individual calls of *deq*. Modify locale *Queue* as follows:

locale *Queue* begin

type_synonym 'a queue = "'a list * 'a list"

definition "init = ([],[])"

fun *balance* :: "'a queue \Rightarrow 'a queue" where

"*balance*(*xs*,*ys*) = (if size *xs* \leq size *ys* then (*xs*,*ys*) else ([], *ys* @ rev *xs*))"

fun *enq* :: "'a \Rightarrow 'a queue \Rightarrow 'a queue" where

"*enq* *a* (*xs*,*ys*) = *balance* (*a*#*xs*, *ys*)"

fun *deq* :: "'a queue \Rightarrow 'a queue" where

"*deq* (*xs*,*ys*) = *balance* (*xs*, tl *ys*)"

Again, we count only the newly allocated list cells.

fun *t_balance* :: "'a queue \Rightarrow nat" where

"*t_balance* (*xs*,*ys*) = (if size *xs* \leq size *ys* then 0 else size *xs* + size *ys*)"

fun *t_enq* :: "'a \Rightarrow 'a queue \Rightarrow nat" where

"*t_enq* *a* (*xs*,*ys*) = 1 + *t_balance* (*a*#*xs*, *ys*)"

fun *t_deq* :: "'a queue \Rightarrow nat" where

"*t_deq* (*xs*,*ys*) = *t_balance* (*xs*, tl *ys*)"

- Start over with showing functional correctness. Hint: You will require an invariant.

fun *invar* :: "'a queue \Rightarrow bool"

fun *abs* :: "'a queue \Rightarrow 'a list"

lemma [simp]: "*invar* *init*"

lemma [simp]: "*invar* *q* \Longrightarrow *invar* (*enq* *x* *q*)"

lemma [simp]: "*invar* *q* \Longrightarrow *invar* (*deq* *q*)"

lemma [simp]: "*abs* *init* = []"

lemma [simp]: "*invar* *q* \Longrightarrow *abs* (*enq* *x* *q*) = *x*#*abs* *q*"

lemma [simp]: "*invar* *q* \Longrightarrow *abs* (*deq* *q*) = butlast (*abs* *q*)"

- Next, define a suitable potential function Φ , and prove that the amortized complexity of *enq* is ≤ 3 and of *deq* is ≤ 0 .

```

fun  $\Phi$  :: "'a queue  $\Rightarrow$  int"
lemma  $\Phi$ _non_neg: " $\Phi$  t  $\geq$  0"
lemma  $\Phi$ _init: " $\Phi$  init = 0"
lemma a_enq: " $t_{enq}$  a q +  $\Phi$ (enq a q) -  $\Phi$  q  $\leq$  3"
lemma a_deq: " $t_{deq}$  q +  $\Phi$ (deq q) -  $\Phi$  q  $\leq$  0"

```

Finally, show that a sequence of enqueue and dequeue operations requires linear cost in its length:

```

datatype 'a opr = ENQ 'a | DEQ
fun execute :: "'a queue  $\Rightarrow$  'a opr list  $\Rightarrow$  'a queue"
  where
    "execute q [] = q"
  | "execute q (ENQ x#ops) = execute (enq x q) ops"
  | "execute q (DEQ#ops) = execute (deq q) ops"

Count only list cell allocations!
fun t_execute :: "'a queue  $\Rightarrow$  'a opr list  $\Rightarrow$  nat"

lemma t_execute: "t_execute init ops  $\leq$  3*length ops"

```

Homework 12 Dynamic Tables with real-valued Potential

Submission until Friday, 21. 7. 2017, 11:59am.

In file *Thys/Amortized_Examples* in the repository there is a formalization of dynamic tables in locale *Dyn_Tab* with the potential function $\Phi(n, l) = 2*n - l$ and a discussion of why this is tricky. The standard definition you find in textbooks does not rely on cut-off subtraction on *nat* but uses standard real numbers:

```

type_synonym tab = "nat  $\times$  nat"

fun  $\Phi$  :: "tab  $\Rightarrow$  real" where
  " $\Phi$  (n,l) = 2*(real n) - real l"

```

Start with the locale *Dyn_Tab* in file *Thys/Amortized_Examples* but use the above definition of $\Phi :: \text{tab} \Rightarrow \text{real}$. A number of proofs will now fail because the invariant is now too weak. Find a stronger invariant such that all the proofs work again.